## Introduction to basic accelerator physics

## Review of Linear Accelerator Optics

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 Lawrence Berkeley National Laboratory- Outline:
-Motivation
-Transverse optics
-Hill Equation
-Tracking
-Longitudinal optics
-Radiation


## Motivation

* This course will finish on many areas of transverse (and longitudinal) single (and multiple) particle dynamics
* Most of you will have learned all fundamentals
* Still would like to remind you of all concepts, to make rest of the week easier to follow
* For transverse dynamics will introduce lattice functions in two different ways (including the one usually used in lattice codes)
* Do not get discouraged by this pretty dense lecture, rest of the week will be much more practical - and does not require that you completely understand everything in this recap


## Concepts

## Want to touch on a number of concepts including:

- Closed orbit
- Betatron tune
- Dispersion
- Momentum compaction
- Transfer matrix
- Twiss parameters and phase advance
- Chromaticity
- Synchrotron Radiation
- Energy spread
- (Equilibrium) Emittance
- Synchrotron Oscillations


## Transverse Beamdynamics Terminology

* Linear beamdynamics (today) determined by:
- Dipoles
- Quadrupoles (lenses)
- Solenoids
- rf-resonators
- (synchrotron radiation)
* Nonlinear (Thursday):
- Sextupoles, higher multipoles, errors, insertion devices (undulators/wigglers), stochastic nature of SR, ...
* Trajectory/Orbit - (single pass/periodic)
- Closed orbit: closed, periodic trajectory around a ring (closes after one turn in position and angle).
- Particles that deviate from the closed orbit will oscillate about it (transverse: Betatron oscillations)


## Particle Storage Rings

In a particle storage rings, charged particles circulate around the ring in bunches for a large number of turns.

Optics elements


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## Equations of Motion in a Storage Ring

The motion of each charged particle is determined by the electric and magnetic forces that it encounters as it orbits the ring:

- Lorentz Force

$$
F=m a=e(E+v \times B),
$$

$m$ is the relativistic mass of the particle,
$e$ is the charge of the particle,
$v$ is the velocity of the particle,
$a$ is the acceleration of the particle,
$E$ is the electric field and,
$B$ is the magnetic field.

## Typical Magnet Types

There are several magnet types that are used in storage rings:
Dipoles $\rightarrow$ used for guiding

$$
\begin{aligned}
& B_{x}=0 \\
& B_{y}=B_{o}
\end{aligned}
$$



Quadrupoles $\rightarrow$ used for focussing

$$
\begin{aligned}
& B_{x}=K y \\
& B_{y}=-K x
\end{aligned}
$$



Sextupoles $\rightarrow$ used for chromatic correction

$$
\begin{aligned}
& B_{x}=2 S x y \\
& B_{y}=S\left(x^{2}-y^{2}\right)
\end{aligned}
$$



## Practical Magnet Examples at the ALS




Quadrupoles

Dipoles


Sextupoles

## Two approaches

There are two approaches to introduce the motion of particles in a storage ring
3. The traditional way in which one begins with Hill's equation, defines beta functions and dispersion, and how they are generated and propagate, ...
5. The way that our computer models actually do it

I will begin with the first way (as a very brief recap) but spend most of the time with the second approach

Change dependent variable from time to longitudinal position, $s$

Coordinate system used to describe the motion is usually locally Cartesian or cylindrical


Typically the coordinate system chosen is the one that allows the easiest field representation

## First approach - traditional one

This approach (differential equations) provides some insights into concepts but is very limited in usefulness for actual calculations

We begin with on-energy no coupling case. The beam is transversely focused by quadrupole magnets. The horizontal linear equation of motion is

$$
\begin{aligned}
& \frac{d^{2} x}{d s^{2}}=-k(s) x, \\
& \text { where } k=\frac{B_{T}}{(B \rho) a}, \text { with } \\
& B_{T} \text { being the pole tip field } \\
& a \text { the pole-tip radius, and } \\
& B \rho[\mathrm{~T}-\mathrm{m}] \approx 3.356 p[\mathrm{GeV} / \mathrm{c}]
\end{aligned}
$$

## Hills equation

The solution can be parameterized by a pseudoharmonic oscillation of the form

$$
\begin{aligned}
& x_{\beta}(s)=\sqrt{\varepsilon} \sqrt{\beta(s)} \cos \left(\varphi(s)+\varphi_{0}\right) \\
& x_{\beta}^{\prime}(s)=-\sqrt{\varepsilon} \frac{\alpha}{\sqrt{\beta(s)}} \cos \left(\varphi(s)+\varphi_{0}\right)-\frac{\sqrt{\varepsilon}}{\sqrt{\beta(s)}} \sin \left(\varphi(s)+\varphi_{0}\right)
\end{aligned}
$$

where $\beta(s)$ is the beta function,
$\alpha(s)$ is the alpha function,
$\varphi_{x, y}(s)$ is the betatron phase, and
$\varepsilon$ is an action variable

$$
\varphi=\int_{0}^{s} \frac{d s}{\beta}
$$

## Example of Twiss parameters and trajectories








## Twiss Parameters and Phase Advance

## In addition to $\beta$ there is $\alpha$ and $\gamma$ :

$$
\begin{aligned}
& \alpha=-\frac{\beta^{\prime}}{2}, \\
& \gamma=\frac{1+\alpha^{2}}{\beta}
\end{aligned}
$$

$$
\frac{d^{2} u(t)}{d t^{2}}+\frac{\omega_{0}}{Q} \frac{d u(t)}{d t}+\omega_{0}^{2} u(t)=\frac{F}{m} \cos (\omega t)
$$

* The general solution is a sum of a transient (the solution for damped undriven harmonic oscillator, homogeneous ODE) that depends on initial conditions, and a steady state (particular solution of the nonhomogenous ODE) that is independent of initial conditions and depends only on driving frequency, driving force, restoring force, damping force, Damped harmonic oscillator:



## Equations of motion



Change dependent variable from time to longitudinal position, s

Coordinate system used to describe the motion is usually locally Cartesian or cylindrical


Typically the coordinate system chosen is the one that allows the easiest field representation

## Integrate

## Integrate through the elements

Use the following coordinates*

$$
x, x^{\prime}=\frac{d x}{d s}, y, y^{\prime}=\frac{d y}{d s}, \delta=\frac{\Delta p}{p_{0}}, \tau=\frac{\Delta L}{L}
$$


*Note sometimes one uses canonical momentum rather than $x^{\prime}$ and $y^{\prime}$

A closed orbit is defined as an orbit on which a particle circulates around the ring arriving with the same position and momentum that it began.


In every working story ring there exists at least one closed orbit.

## Approximation

Everything up to now there was general. No discussion of the field representation or the integrator. In many codes simplifications are made.

- The velocity of the particle is the speed of light $\boldsymbol{\rightarrow} v=c$
- The magnetic field is isomagnetic. Piecewise constant in $s$

- The angle of the particles with respect to the reference particle is small and can assume that $\theta=\tan \theta$



## Transfer Matrix

One can write the linear transformation between one point in the storage ring (i) to another point (f) as


$$
\binom{x}{x^{\prime}}_{f}=\left(\begin{array}{cc}
C & S \\
C^{\prime} & S^{\prime}
\end{array}\right)\binom{x}{x^{\prime}}_{i}
$$

this is for the case of uncoupled horizontal motion. One can extend this to $4 \times 4$ or $6 \times 6$ cases.

## Piecewise constant magnetic fields

* General transfer matrix from $\mathrm{s}_{0}$ to s

$$
\binom{u}{u^{\prime}}_{s}=\mathcal{M}\left(s \mid s_{0}\right)\binom{u}{u^{\prime}}_{s_{0}}=\left(\begin{array}{cc}
C\left(s \mid s_{0}\right) & S\left(s \mid s_{0}\right) \\
C^{\prime}\left(s \mid s_{0}\right) & S^{\prime}\left(s \mid s_{0}\right)
\end{array}\right)\binom{u}{u^{\prime}}_{s_{0}}
$$

* Note that

$$
\operatorname{det}\left(\mathcal{M}\left(s \mid s_{0}\right)\right)=C\left(s \mid s_{0}\right) S^{\prime}\left(s \mid s_{0}\right)-S\left(s \mid s_{0}\right) C^{\prime}\left(s \mid s_{0}\right)=1
$$

which is always true $\mathrm{f} \mathcal{M}\left(s_{0} \mid s_{0}\right)=\left(\begin{array}{ll}1 & 0 \\ 0 & 1\end{array}\right)=\mathcal{I} \mathbf{3}$

* Note also that

* The accelerator can be build by a series of matrix multiplications


from $\mathrm{s}_{0}$ to $\mathrm{s}_{1}$
from $\mathbf{s}_{0}$ to $\mathbf{s}_{2}$
from $\mathbf{s}_{\mathbf{0}}$ to $\mathbf{s}_{\mathbf{3}}$



## Examples of transfer matrices

Drift of length $L$

$$
\boldsymbol{R}_{\text {drift }}=\left(\begin{array}{ll}
1 & \boldsymbol{L} \\
0 & 1
\end{array}\right)
$$

The matrix for a focusing quadrupole of gradient $k=(\partial B / \partial x) /(B \rho)$ and of length $\boldsymbol{l}_{q}$

$$
R_{Q_{\text {uad }}}=\left(\begin{array}{cc}
\cos \phi & \sin \phi / \sqrt{|k|} \\
-\sqrt{|k|} \sin \phi & \cos \phi
\end{array}\right)
$$

The matrix for a zero length thin quadrupole $K=|\boldsymbol{k}| \boldsymbol{l}_{q}$

$$
\boldsymbol{R}_{\text {thin-lens }}=\left(\begin{array}{cc}
1 & 0 \\
-\boldsymbol{K} & 1
\end{array}\right)
$$

## Magnetic lenses: Quadrupoles

Magnetic focusing fields:



* Thin lens representation


A closed orbit is defined as an orbit on which a particle circulates around the ring arriving with the same position and momentum that it began.


In every working story ring there exists at least one closed orbit.

## Generate a one-turn Map Around the Closed Orbit

A one-turn map, $R$, maps a set of initial coordinates of a particle to the final coordinates, one-turn later.

$$
\begin{aligned}
& x_{f}=x_{i}+\frac{d x_{f}}{d x_{i}}\left(x_{i}-x_{i, c o}\right)+\frac{d x_{f}}{d x_{i}^{\prime}}\left(x_{i}^{\prime}-x_{i, c o}^{\prime}\right)+\ldots \\
& x_{f}^{\prime}=x_{i}^{\prime}+\frac{d \dot{x}_{f}^{\prime}}{d x_{i}}\left(x_{i}-x_{i, c o}\right)+\frac{d x_{f}^{\prime}}{d x_{i}^{\prime}}\left(x_{i}^{\prime}-x_{i, c o}^{\prime}\right)+\ldots
\end{aligned}
$$

The map can be calculated by taking orbits that have a slight deviation from the closed orbit and tracking them around the ring.
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## Computation of beta-functions and tunes

The one turn matrix (the first order term of the map) can be written

$$
\boldsymbol{R}_{\text {one-turn }}=\left(\begin{array}{cc}
\boldsymbol{C} & \boldsymbol{S} \\
\boldsymbol{C}^{\prime} & \boldsymbol{S}^{\prime}
\end{array}\right)=\left(\begin{array}{cc}
\boldsymbol{\operatorname { c o s }} \varphi+\alpha \sin \varphi & \beta \sin \varphi \\
-\gamma \sin \phi & \boldsymbol{\operatorname { c o s }} \varphi-\alpha \sin \varphi
\end{array}\right)
$$

Where $\alpha, \beta, \gamma$ are called the Twiss parameters

$$
\alpha=-\frac{\beta^{\prime}}{2},
$$

and the betatron tune, $v=\phi /\left(2^{*} \pi\right)$

$$
\gamma=\frac{1+\alpha^{2}}{\beta}
$$

For long term stability $\phi$ is real $\rightarrow$

$$
|T R(R)|=|2 \cos \phi|<2
$$

In an linear uncoupled machine the turn-by-turn positions and angles of the particle motion will lie on an ellipse

$$
\begin{aligned}
& \text { Area of the ellipse, } \varepsilon: \\
& x_{\beta}^{\prime}(s)=\sqrt{\varepsilon} \sqrt{\beta(s)} \cos \left(\varphi(s)+\varphi_{0}\right) \\
& x_{\beta}^{\prime}(s)=-\sqrt{\varepsilon} \frac{\alpha}{\sqrt{\beta(s)}} \cos \left(\varphi(s)+\varphi_{0}\right)-\frac{\sqrt{\varepsilon}}{\sqrt{\beta(s)}} \sin \left(\varphi(s)+\varphi_{0}\right)+2 \alpha x x^{\prime}+\beta \boldsymbol{x}^{\prime 2}
\end{aligned}
$$

## Emittance Definition

* Consider the decoupled case and use the $\{w, w\}$ plane where $w$ can be either $x$ or $y$ :
- The emittance is the phase space area occupied by the system

$$
\varepsilon_{w}=\frac{A_{w w^{\prime}}}{\pi} \quad w=x, y
$$



* $\quad x^{\prime}$ and $y^{\prime}$ are conjugate to $x$ and $y$ when $B_{z}=0$ and in absence of acceleration. In this case, we can immediately apply the Liouville theorem:
- For such a system the emittance is an invariant of the motion.
* This specific case is very common in accelerators:
- For most of the elements in a beam transferline, such as dipoles, quadrupoles, sextupoles, ..., the above conditions apply and the emittance is conserved.


## Emittance Definition/Statistical

* Emittance defined as the phase space area occupied by an ensemble of particles
* Example: In the transverse coordinates it is the product of the size (cross section) and the divergence of a beam (at beam waists).
* Emittance can be defined as a statistical quantity (beam is composed of finite number of particles)


$$
\begin{aligned}
& \mathcal{E}_{\text {geometric,rms }}=\sqrt{\left\langle x^{2}\right\rangle\left\langle x^{\prime 2}\right\rangle-\left\langle x x^{\prime}\right\rangle^{2}} \\
& \qquad\left\langle x^{2}\right\rangle=\frac{\sum_{n=1}^{N} x_{n}^{2}}{N} \cong \frac{\int x^{2} f_{2 D}\left(x, x^{\prime}\right) d x d x^{\prime}}{\int f_{2 D}\left(x, x^{\prime}\right) d x d x^{\prime}}
\end{aligned}
$$

This is equivalent to associate to the real beam an equivalent or phase ellipse in the phase space with area $\pi \varepsilon_{r m s}$ and equation:

$$
\frac{\left\langle x^{\prime 2}\right\rangle}{\varepsilon_{r m s}} x^{2}+\frac{\left\langle x^{2}\right\rangle}{\varepsilon_{r m s}} x^{\prime 2}-2 \frac{\left\langle x x^{\prime}\right\rangle}{\varepsilon_{r m s}} x x^{\prime}=\varepsilon_{r m s}
$$

## Transport of the beam ellipse

## Beam ellipse matrix

$$
\sum_{\text {beam }}^{x}=\varepsilon_{x}\left(\begin{array}{cc}
\beta & -\alpha \\
-\alpha & \gamma
\end{array}\right)
$$

## Transformation of the beam ellipse matrix

$$
\sum_{\text {beam }, f}^{x}=\boldsymbol{R}_{x, i-f} \sum_{\text {beam,i}}^{x} \boldsymbol{R}_{x, i-f}^{T}
$$

## What happens off-energy ? Chromatic Aberration

## Focal length of the lens is dependent upon energy



Larger energy particles have longer focal lengths

## Chromatic Aberration Correction



By including dispersion and sextupoles it is possible to compensate (to first order) for chromatic aberrations


The sextupole gives a position dependent Quadrupole

$$
\begin{aligned}
& B_{x}=2 S x y \\
& B_{y}=S\left(x^{2}-y^{2}\right)
\end{aligned}
$$



## Chromatic Aberration Correction

Chromaticity, $v^{\prime}$, is the change in the tune with energy

$$
v^{\prime}=\frac{d v}{d \delta}
$$

Sextupoles can change the chromaticity

$$
\begin{aligned}
& \Delta v_{x}^{\prime}=\frac{1}{2 \pi}\left(\Delta \boldsymbol{S} \beta_{x} \boldsymbol{D}_{x}\right) \\
& \Delta v_{y}^{\prime}=-\frac{1}{2 \pi}\left(\Delta \boldsymbol{S} \beta_{y} \boldsymbol{D}_{x}\right) \\
& \text { where }
\end{aligned}
$$

$$
\Delta S=\left(\partial^{2} B_{y} / \partial x^{2}\right) \text { gength } /(2 B \rho)
$$

Now to longitudinal Motion: Integrate - Recap from Before


Integrate through the elements - longitudinally same way as transversely

Use the following coordinates*

$$
x, x^{\prime}=\frac{d x}{d s}, y, y^{\prime}=\frac{d y}{d s}, \delta=\frac{\Delta p}{p_{0}}, \tau=\frac{\Delta L}{L}
$$


*Note sometimes one uses canonical momentum rather than $x^{\prime}$ and $y^{\prime}$

## Examples of Element Transfer Matrix

## Drift

## thin RF cavity

## coordinate

 vector$\left(\begin{array}{cccccc}1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & -\omega \frac{e \hat{\hat{V}}}{p c} \cos \phi & 1\end{array}\right)$


Also: path length effect in dipole However, dipole transfer map is pretty confusing, so I will not write it down here ... (quantitatively, see following slides)

## How long does it take to complete revolution?

Assume that the energy is fixed $\rightarrow$ no cavity or damping - Find the closed orbit for a particle with slightly different energy than the nominal particle. The dispersion is the difference in closed orbit between them normalized by the relative momentum difference

$$
\Delta \mathrm{p} / \mathrm{p}=0
$$

$$
\begin{aligned}
x & =D_{x} \frac{\Delta p}{p}, y=D_{y} \frac{\Delta p}{p} \\
x^{\prime} & =D_{x}^{\prime} \frac{\Delta p}{p}, y^{\prime}=D_{y}^{\prime} \frac{\Delta p}{p}
\end{aligned}
$$

## Momentum Compaction Factor

Momentum compaction, $\alpha$, is the change in the closed orbit length as a function of momentum.


$$
\begin{aligned}
\frac{\Delta L}{L} & =\alpha \frac{\Delta p}{p} \\
\alpha & =\int_{0}^{L_{0}} \frac{D_{x}}{\rho} d s
\end{aligned}
$$



* In the example (sector bending magnet) $L>L_{0}$ so that $\alpha_{C}>0$. Higher energy particles will leave the magnet later.


## Ballistic time-of-flight

* Consider two particles with different momentum on parallel trajectories:

$$
p_{1}=p_{0}+\Delta p
$$



* At a given time $t$ :

$$
L_{1}=\left(\beta_{0}+\Delta \beta\right)_{c t} \quad L_{0}=\beta_{0} c t \quad \Rightarrow \frac{\Delta L}{L_{0}}=\frac{L_{1}-L_{0}}{L_{0}}=\frac{\Delta \beta}{\beta_{0}}
$$

* But:

$$
\begin{aligned}
& p=\beta \gamma m_{0} c \Rightarrow \Delta p=m_{0} c \Delta(\beta \gamma)=m_{0} c \gamma^{3} \Delta \beta \\
\Rightarrow & \frac{\Delta p}{p_{0}}=\gamma^{2} \frac{\Delta \beta}{\beta} \quad \square \quad \frac{\Delta L}{L_{0}}=\frac{1}{\gamma^{2}} \frac{\Delta p}{p_{0}}
\end{aligned}
$$

* The ballistic path length dependence on momentum is important everywhere, not just in bending magnets.
* Higher momentum particles are faster, i.e. precede the ones with lower momentum.
* The effect vanishes for relativistic particles.


## Phase Slippage, Isochronicity

* Combining the previous two results we obtain the overall

$$
\frac{\Delta s}{L_{0}}=-\left(\frac{1}{\gamma^{2}}-\alpha_{C}\right) \frac{\Delta p}{p_{0}}=-\eta_{C} \frac{\Delta p}{p_{0}}
$$ phase slippage factor

* If $\frac{1}{\gamma^{2}}=\alpha$,
the circulation time does not depend on the particle momentum any more. One calls this isochronous transport


## Energy Gain/Loss

* The change in energy for a particle that moves from $A$ to $B$ is given by:


$$
\Delta E=q \int_{0}^{L} \bar{E}_{F}(\bar{r}, t) \cdot d \bar{s}=q V
$$

* Now define a voltage V such that $V$ depends only on the particle trajectory. It includes the contribution of every electric field (RF fields, space charge fields, fields due to the interaction with the vacuum chamber, ...)
* In addition there are changes in energy $U(E)$ that depend also on the particle energy (e.g. radiation emitted by a particle under acceleration synchrotron radiation)
* The total change in energy is given by the sum of the two terms:

$$
\Delta E_{T}=q V+U(E)
$$

## ALS example of RF cavity



* Cavities replenish the energy loss due to synchrotron radiation



## Rate of Energy Change



The energy variation for the reference particle is given by:

$$
\Delta E_{T}\left(s_{0}\right)=q V\left(s_{0}\right)+U\left(E_{0}\right)
$$

For particle with energy $E=E_{0}+\Delta E$ and orbit position $s=s_{0}+\Delta s$ :

$$
\Delta E_{T}(s)=q V\left(s_{0}+\Delta s\right)+U\left(E_{0}+\Delta E\right) \cong q V\left(s_{0}\right)+\left.q \frac{d V}{d s}\right|_{s_{0}} \Delta s+U\left(E_{0}\right)+\left.\frac{d U}{d E}\right|_{E_{0}} \Delta E
$$

Where the last expression holds for the case where $\Delta s \ll L_{0}$ (reference orbit length) and $\Delta E \ll E_{0}$.
In this approximation we can express the average rate of change of the energy respect to the reference particle energy by:

$$
\frac{d \Delta E}{d t} \cong \frac{\Delta E_{T}(s)-\Delta E_{T}\left(s_{0}\right)}{T_{0}}
$$

where $T_{0}=\frac{L_{0}}{\beta_{0}} \quad$ with $\quad L_{0}=$ lenght of the reference orbit between $A$ and $B$

## Synchrotron Oscillations

## Define the frequency and damping terms:

$$
\Omega^{2}=\left.\eta_{C} \frac{1}{p_{0}} \frac{q}{T_{0}} \frac{d V}{d s}\right|_{s_{0}}
$$

$$
\alpha_{D}=-\left.\frac{1}{2 T_{0}} \frac{d U}{d E}\right|_{E_{0}}
$$

We obtain the equations of motion for the longitudinal plane:

$$
\begin{array}{rr}
\frac{d^{2} \Delta s}{d t^{2}}+2 \alpha_{D} \frac{d \Delta s}{d t}+\Omega^{2} \Delta s=0 & \Delta s \ll L_{0} \\
\Delta E(t)=-\frac{p_{0}}{\eta_{C}} \frac{d \Delta s}{d t} & \Delta E \ll E_{0}
\end{array}
$$

## Small Amplitude: Damped harmonic oscillator

$$
\frac{d^{2} \Delta s}{d t^{2}}+2 \alpha_{D} \frac{d \Delta s}{d t}+\Omega^{2} \Delta s=0
$$

This expression is the well known damped harmonic oscillator equation, which has the general solution:

$$
\Delta s(t) \cong e^{-\alpha_{D} t}\left(A e^{i \Omega t}+B e^{-i \Omega t}\right)
$$

$\alpha_{D}>0 \Leftrightarrow$ damped oscillation
$\alpha_{D}<0 \Leftrightarrow$ anti-damped oscillation

$$
\Omega^{2}>0 \Leftrightarrow \text { stable oscillation }
$$

$$
\Omega^{2}<0 \Leftrightarrow \text { unstable motion }
$$



## Synchronicity/Harmonic Number

* Let's consider a storage ring with reference trajectory of length $L_{0}$ :


$$
\begin{gathered}
V_{R F}(t)=\hat{V} \sin \left(\omega_{R F} t\right) \\
T_{0}=\frac{L_{0}}{\beta c} \quad T_{R F}=\frac{1}{f_{R F}}=\frac{2 \pi}{\omega_{R F}}
\end{gathered}
$$



$$
T_{0}=h T_{R F} \Rightarrow f_{0}=\frac{f_{R F}}{h}
$$

Synchronicity Condition
The integer $h$ is called the harmonic number

[^0]
## Longitudinal Phasespace



We just found:

$$
\varphi=\hat{\varphi} \cos (\Omega t+\psi)
$$

$$
\delta=\frac{\hat{\varphi} \Omega}{h \omega_{0} \eta_{C}} \sin (\Omega t+\psi)
$$

4

$$
\frac{\varphi^{2}}{\hat{\varphi}^{2}}+\delta^{2}\left(\frac{h \omega_{0} \eta_{C}}{\hat{\varphi} \Omega}\right)^{2}=1
$$

This equation represents an ellipse in the longitudinal phase space $\{\varphi, \delta\}$


With damping:

$$
\begin{gathered}
\varphi=\hat{\varphi} e^{-\alpha_{D} t} \cos (\Omega t+\psi) \\
\delta=\frac{\hat{\varphi} \Omega}{h \omega_{0} \eta_{C}} e^{-\alpha_{D} t} \sin (\Omega t+\psi)
\end{gathered}
$$



In rings with negligible synchrotron radiation (or with negligible non-Hamiltonian forces, the longitudinal emittance is conserved.

This is the case for heavy ion and for most proton machines.

## Large Amplitudes/Separatrix



So far we have used the small oscillation approximation where:

$$
\Delta E_{T}(\psi)=q V\left(\varphi_{S}+\varphi\right)=q \hat{V} \sin \left(\varphi_{S}+\varphi\right) \cong q V\left(\varphi_{S}\right)+\left.q \frac{d V}{d \varphi}\right|_{\varphi_{S}} \varphi=q \hat{V} \varphi_{S}+q \hat{V} \varphi
$$

In the more general case of larger phase oscillations:

$$
\Delta E_{T}(\psi)=q V\left(\varphi_{S}+\varphi\right) \cong q \hat{V} \sin \left(\varphi_{S}+\varphi\right) \quad \text { And by Numerical integration: }
$$



- For larger amplitudes, trajectories in the phase space are not ellipsis anymore.
- Stable and unstable orbits exist. The two regions are separated by a special trajectory called separatrix
- Larger amplitude orbits have smaller synchrotron frequencies
- Radiated power increases at higher velocities
- Radiation becomes more focused at higher velocities


Case I: $\frac{\mathrm{v}}{\mathrm{c}} \ll 1$
At low electron velocity (nonrelativistic case) the radiation is emitted in a non-directional pattern


When the electron velocity approaches the velocity of light, the emission pattern is folded sharply forward. Also the radiated power goes up dramatically

## Time compression

Electron with velocity $\beta$ emits a wave with period $T_{\text {emit }}$ while the observer sees a different period $T_{\text {obs }}$ because the electron was moving towards the observer


$$
T_{\text {obs }}=(1-\mathbf{n} \cdot \boldsymbol{\beta}) T_{\text {emit }}
$$

The wavelength is shortened by the same factor

$$
\lambda_{\text {obs }}=(1-\beta \cos \theta) \lambda_{e m i t}
$$

in ultra-relativistic case, looking along a tangent to the trajectory


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## Radiation



The power emitted by a particle is

$$
P_{S R}=\frac{2}{3} \alpha \hbar c^{2} \frac{\gamma^{4}}{\rho^{2}}
$$

and the energy loss in one turn is

$$
\boldsymbol{U}_{0}=\frac{4 \pi}{3} \alpha \hbar c \frac{\gamma^{4}}{\rho^{2}}
$$




## Radiation damping

Energy damping:

$$
\left.\alpha_{D}>0 \quad \alpha_{D}=-\left.\frac{1}{2 T_{0}} \frac{d U}{d E}\right|_{E_{0}} \quad \quad \right\rvert\, \sqrt{\left.\frac{d U}{d E}\right|_{E_{0}}<0}
$$

Larger energy particles lose more energy

$$
P_{S R}=\frac{2}{3} \alpha \hbar c^{2} \frac{\gamma^{4}}{\rho^{2}}
$$

- Typically, synchrotron radiation damping is very efficient in electron storage rings and negligible in proton machines.
- The damping time $1 / \alpha_{D}(\sim$ ms for e-, $\sim 13$ hours LHC at 7 TeV ) is usually much larger than the period of the longitudinal oscillations $1 / 2 \pi \Omega(\sim \mu s)$. This implies that the damping term can be neglected when calculating the particle motion for $t \ll 1 / \alpha_{D}$ :

$$
\frac{d^{2} \Delta s}{d t^{2}}+\Omega^{2} \Delta s=0
$$

Harmonic oscillator equation

## Radiation damping

## Energy damping:

Larger energy particles lose more energy

$$
P_{S R}=\frac{2}{3} \alpha \hbar c^{2} \frac{\gamma^{4}}{\rho^{2}}
$$

Transverse damping:
Energy loss is in the direction of motion while the restoration in the s direction


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## Quantum excitation - Longitudinally

The synchrotron radiation emitted as photons, the typical photon energy is

$$
u_{c}=\hbar \omega_{c}=\frac{3}{2} \hbar c \frac{\gamma^{3}}{\rho}
$$

The number of photons emitted is

$$
N=\frac{4}{9} \alpha c \frac{\gamma}{\rho}
$$

With a statistical uncertainty of $\sqrt{N}$
The equilibrium energy spread and bunch length is

$$
\left(\frac{\sigma_{e}}{E}\right)^{2}=1.468 \cdot 10^{-6} \frac{E^{2}}{\boldsymbol{J}_{\varepsilon} \rho} \text { and } \sigma_{L}=\frac{\alpha \boldsymbol{R}}{\boldsymbol{f}_{0}} \sigma_{e}
$$

> Advanced Light Source

## Quantum Excitation - Transversely

## Particles change their energy in a region of dispersion

 undergoes increase transverse oscillations. This balanced by damping gives the equilibrium emittances.

Betatron phaseadvance

The beam size is then

$$
\sigma_{x}=\sqrt{\beta_{x} \varepsilon+\left(D_{x} \frac{\sigma_{e}}{E}\right)^{2}}
$$

## Time Scales for Particle Dynamics in Rings

* At this point we have discussed the motion of a particle in an accelerator for all 6 phase space dimensions (4 transverse dimensions and 2 longitudinal ones)
* An important effect is that the time scales for different phenomena are quite different:
- Damping: several ms for electrons, ~ infinity for heavier particles
- Betatron oscillations: ~ tens of ns
- Synchrotron oscillations: ~ tens of $\mu \mathrm{s}$
- Revolution period: ~ hundreds of ns to $\mu \mathrm{s}$


## Summary

* Introduced many concepts of linear beam dynamics
* Matrix (transverse) beam transport approach is helpful to calculate simple problems by hand
* Computer codes use an extension of this approach (nonlinear integrators for individual elements, symplectic, ...)
* Find closed orbit - generate map around closed orbit - lattice functions
* Historic and text book approach of hill's equation is not very useful for practical purposes (either calculations by hand or computer codes)
Thanks to David Robin for illustrations and slides


## List of Literature/Text Books



* Particle Accelerator Physics I (2 ${ }^{\text {nd }}$ edition, 1998), by Helmut Wiedemann, Springer (part II: nonlinear and ... is beyond the scope of this lecture)
* D.A. Edwards and M.J. Syphers, An Introduction to the Physics of High Energy Accelerators, John Wiley \& Sons (1993)
* Accelerator Physics, S.Y. Lee, World Scientific, Singapore, 1999 (ISBN 9810237103)
* Many nice proceedings of CERN accelerator schools can be found at http://cas.web.cern.ch/cas/CAS Proceedings.html , for the purpose of this class especially CERN 94-01 v1 + v2
Material for further reading (if you got really interested):
- Particle Accelerator Physics II, H. Wiedemann, Springer (nonlinear ...)
- CERN 95-06 v1 + v2 (Advanced Class)
- CERN 98-04 (Synchrotron Radiation+Free Electron Lasers)
- Physics of Collective Beam Instabilities ..., A.W. Chao, John Wiley and Sons, New York, 1993 (ISBN 0471551848 ) and http://www.slac.stanford.edu/~achao/wileybook.html


[^0]:    Advanced Light Source

